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VOLUNTARY ANNOUNCEMENT

BUSINESS UPDATE - ROBOTICS PLATFORM OPERATION BUSINESS

ENTERING INTO THE COOPERATION AGREEMENT WITH THE INSTITUTE OF MECHANICS, CHINESE ACADEMY OF SCIENCES

This announcement is made by Hony Media Group (the “**Company**”, together with its subsidiaries, the “**Group**”) on a voluntary basis to provide information to the Company’s shareholders and potential investors regarding the Group’s latest business developments.

I. ENTERING INTO THE COOPERATION AGREEMENT WITH THE INSTITUTE OF MECHANICS, CHINESE ACADEMY OF SCIENCES

The board of directors (the “**Directors**”) of the Company (the “**Board**”) is pleased to announce that AIROBO (Chengdu) Technology Co., Ltd.* (艾諾博（成都）科技有限公司), an indirect subsidiary of the Group, has entered into the cooperation agreement with The Institute of Mechanics (“**IMECH**”), Chinese Academy of Sciences (“**CAS**”) for a term of five years. The parties intend to carry out long-term cooperation centered on robot operation mechanisms, spatial intelligence, simulation deduction, multi-robot collaboration, scene data closed-loop, and technological achievement transformation in complex scenarios, so as to promote the deep integration of scientific innovation and industrial innovation.

II. COOPERATION POSITIONING AND KEY COOPERATION DIRECTIONS

The cooperation between the parties will focus on the safe, reliable, and efficient operation of service robots and related intelligent equipment in complex real-world environments, such as communities, commercial sites, parks, hotels, and logistics settings, establishing replicable technical systems, engineering standards, evaluation methods, and demonstration achievements.

The key cooperation directions between the parties include:

- **Joint Establishment of a Robotics Operations Project Laboratory:** The parties will jointly build a dedicated laboratory oriented toward actual service robot operational scenarios. Experimental work will be conducted around on-site robot operations, multi-machine dispatch, scene data validation, operational issue reproduction, and solution iteration and optimization, facilitating technical verification, case study accumulation, and operational technology consolidation.
- **Joint Technical Research and Breakthroughs:** The parties will jointly formulate scientific problems and engineering tasks focusing on motion and contact mechanics in complex environments, multi-physics coupling modeling, robot dynamics and control, dynamic obstacle prediction, multi-robot collaboration, human-robot collaborative safety, embodied AI scene learning, scientific machine learning, as well as reliability and safety evaluations.
- **Joint Construction of an All-domain Intelligent Operations Platform for Property and Commercial Robotics Scenarios:** Promoting capacity building across unified connection for multi-brand heterogeneous robots, map and spatial models, task orchestration and collaborative dispatch, elevator control and access/doorway coordination, operational status monitoring, anomaly early warning, data closed-loop, and operational evaluation.
- **Joint Advancement of a Robotics Scene Application R&D Platform:** Focusing on real-world scenarios such as communities, commercial sites, parks, hotels, and logistics settings to conduct requirement definition, prototype validation, system testing, performance evaluation, and iterative optimization.
- **Joint Advancement of Experimental Research in Spatial Intelligence and Robotics Technology:** Conducting research on spatial physical modeling, real-scene simulation deduction, digital twins, wheel-leg composite motion control, high-density cluster collaboration, and testing and evaluation methods.
- **Transformation of Scientific and Technological Achievements and Industrial Synergy:** Carrying out pilot scale verification, productization, licensing implementation, capital contribution via valuation, technical services, or other compliant transformation activities centered on mature achievements.
- **Talent Cultivation and Academic Exchange:** Cultivating interdisciplinary talent through joint research projects, engineering practices, expert consultations, special seminars, and scientific researcher exchanges.

III. REASONS FOR AND BENEFITS OF THE COOPERATION

IMECH, CAS is a research institute under CAS founded in 1956. It is a comprehensive national mechanics research base guided by Professor Qian Xuesen's conception of engineering science, possessing deep capabilities in fundamental research, engineering science research, talent cultivation, and transformation of scientific and technological achievements.

Through the signing of this cooperation agreement, the Group could establish a long-term, stable, and collaboratively innovative industry-university-research strategic partnership with IMECH, CAS. IMECH, CAS will leverage its strengths in fundamental research in mechanics, engineering science, scientific research platforms, and talent resources; while the Group will leverage its advantages in real-world scenarios, engineering systems, industrial organization, and market transformation. Together, both parties will construct a collaborative innovation chain spanning “fundamental research — key technologies — system validation — demonstration applications — achievement transformation”.

IV. GENERAL

To the best of the Directors’ knowledge, information and belief, having made all reasonable enquiries, IMECH, CAS and its ultimate beneficial owner are third parties independent of the Company and its connected persons.

The specific implementation of the aforesaid cooperation and projects remains subject to subsequent execution of project documents between the parties and actual progress, and is therefore subject to certain uncertainties. The Company will make further announcement(s) in relation to any material progress as and when appropriate in accordance with the Rules Governing the Listing of Securities on the Stock Exchange of Hong Kong Limited and other applicable laws and regulations.

Shareholders and potential investors of the Company are advised to exercise caution when dealing in the securities of the Company.

** Note: The English name of the company is directly translated from its Chinese names and is furnished for identification purpose only. Should any inconsistencies between the Chinese names and the English names exist, the Chinese names shall prevail.*

By Order of the Board
Hony Media Group
HAU Wai Man, Raymond
Company Secretary

Hong Kong, 1 September 2026

As at the date of this announcement, the Board comprises:

Mr. YUEN Hoi Po¹ (CEO), Mr. CHENG Wu¹, Mr. YUEN Kin², Ms. WANG Song Song² and Ms. PAN Min²

¹ *Executive director*

² *Independent non-executive director*

In the case of inconsistency, the English text of this announcement shall prevail over the Chinese text.